

I suggest to break the Message Transport into two distinct layers:

1. Message Abstraction Layer
2. Communication Pattern (or a better name) and move AMS and DTN there (since these are as far as I understand higher level comms protocols/ comms pattern).

The choice of specifying Telerobotics services as MO services, implies that there is always the Message Abstraction Layer (at least conceptually), which allows the switching of the encoding and transport without impacting the higher layers.

Please note that for a concrete deployment/implementation, these conceptual layers can well be merged for performance reasons or to meet other constraints.

This will probably be the likely case for deployments on-board spacecrafts and in the robotic systems with limited computing resources.

+lmartin7676@gmail.com Lindolfo, apologies for the comment overload (since there are three source comments related to Figure 2). I have a version of this diagram, as do you. If we decide which source version to use, and place the source in the new MOIMS-TEL Green Book, Diagrams folder, we can collaborate on editing the diagrams as well.